Estimation of causal effects under the presence of trapdoor variables

Jouni Helske (joint work with Santtu Tikka and Juha Karvanen) University of Jyväskylä

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Introduction

- Great progress has been made in causal identification research
 - Given a causal graph, produces identifying functional of causal effect (if identifiable)
 - Easy-to-use software implementations available, e.g, the causaleffect package in R (Tikka and Karvanen 2017)
- Identifiability only indicates the existence of an estimator
 - Does not take into account the potential problems due to finite data and parameter/model uncertainty

Example graph

- We studied (Helske, Tikka, and Karvanen 2021) how to perform causal estimation with relatively small data under the presence of *trapdoor variable*
- \triangleright Y, X, Z, and W observed, dashed arrows are unobserved



$$P(Y \mid do(X = x)) = \frac{\sum_{W} P(Y \mid x, Z, W) P(x \mid Z, W) P(W)}{\sum_{W} P(x \mid Z, W) P(W)}$$

General approach to estimation

- We estimate the full interventional distribution P(Y | do(X = x)) by simultaneously estimating the terms of the identifying functional via Bayesian methods.
 - ► Takes into account the uncertainty in P(Y | do(X = x)) due to parameter estimation
 - Avoids the plug-in bias due to the potential nonlinearity of the causal formula.

However, we still need to figure out what to do with the variable Z...

Trapdoor variable

$$P(Y \mid do(X = x)) = \frac{\sum_{W} P(Y \mid x, Z, W) P(x \mid Z, W) P(W)}{\sum_{W} P(x \mid Z, W) P(W)}$$

- ▶ Tian and Pearl (2002) show that in this graph P(Y | do(X = x)) is functionally independent of Z.
- In practice we still must choose some value for Z which can lead to bias.
- Here Z is a trapdoor variable with respect to the identifying functional in this graph (for formal definition see Helske, Tikka, and Karvanen (2021)).

Trapdoor variable in linear-Gaussian case

In a linear-Gaussian model, we have

$$W \sim N(a_w, s_w^2),$$

 $(X \mid Z = z, W = w) \sim N(a_x + b_{xz}z + b_{xw}w, s_x^2),$
 $(Y \mid X = x, Z = z, W = w) \sim N(a_y + b_{yx}x + b_{yz}z + b_{yw}w, s_y^2),$

where parameters a., b.., and s. are estimated from the data. This yields

$$\begin{split} E(Y \mid \operatorname{do}(X = x)) &= a_y + \frac{b_{yw} s_x^2}{b_{xw}^2 s_w^2 + s_x^2} a_w - \frac{b_{yw} b_{xw} s_w^2}{b_{xw}^2 s_w^2 + s_x^2} a_x \\ &+ \left(b_{yx} + \frac{b_{yw} b_{xw} s_w^2}{b_{xw}^2 s_w^2 + s_x^2} \right) x \\ &+ \left(b_{yz} - \frac{b_{yw} b_{xw} s_w^2}{b_{xw}^2 s_w^2 + s_x^2} b_{xz} \right) z \end{split}$$

Simulation experiment

- 1. Fix the trapdoor variable Z to the constant z = 0.
- 2. Also estimate P(Z) and use z = E(Z).
- 3. As above, but estimate P(Z | X = x) and use z = E(Z | X = x).
- 4. Use a constraint $b_{yz} = (b_{xz}b_{yw}b_{xw}s_w^2)/(b_{xw}^2s_w^2 + s_x^2)$ so that the contribution of z is fixed to zero (red term in previous slide is zero).
- 5. Use a linear-Gaussian structural equation model (SEM).

Results (1000 replications from data generating process)



References

Helske, Jouni, Santtu Tikka, and Juha Karvanen. 2021.
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